

Math 2J

Lecture 9 - 10/17/12

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Recap

- The **determinant** is a function that assigns a number to a **square** matrix “A” so that
- $det(A) = 0 \Leftrightarrow A$ is singular
 $det(A) \neq 0 \Leftrightarrow A$ is non-singular

Computing a Determinant

- Can be computed by ‘method of diagonals’ for 2×2 and 3×3 .
- For larger matrices, expansion by minors is necessary.

Properties

$$\det(A \cdot B) = \det(A) \cdot \det(B)$$

$$\det(A^T) = \det(A)$$

- You must take care though.

$$\det(A + B) \neq \det(A) + \det(B)$$

One more property

- If 'A' is invertible, then $\det(A^{-1}) = \frac{1}{\det(A)}$
- Proof

$$A^{-1} \cdot A = \mathbb{I} \qquad \mathbb{I} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\det(A^{-1}) \cdot \det(A) = \det(A^{-1} \cdot A) = \det(\mathbb{I}) = 1$$

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

Special Matrices

- Diagonal matrix

$$\det \left(\begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix} \right) = d_1 \cdot d_2 \cdot d_3$$

Special Matrices

- Triangular matrix.

$$\det \begin{pmatrix} \begin{bmatrix} d_1 & a & b \\ 0 & d_2 & c \\ 0 & 0 & d_3 \end{bmatrix} \end{pmatrix} = d_1 \cdot d_2 \cdot d_3$$

$$\det \begin{pmatrix} \begin{bmatrix} d_1 & 0 & 0 \\ a & d_2 & 0 \\ b & c & d_3 \end{bmatrix} \end{pmatrix} = d_1 \cdot d_2 \cdot d_3$$

The determinant and Gaussian Elimination

- Switch two rows - multiply the determinant by (-1)
- Multiply a row by 'c' - multiply the determinant by (c)
- Perform $R_2 \rightarrow aR_1 + bR_2$ - multiply the determinant by (b) .

Collect Thoughts

Equivalent Statements

- $A*x=b$ has a **single unique** solution for any 'b'.
- 'A' has an inverse.
- 'A' is non-singular.
- 'A' can be turned into \mathbb{I} using Gaussian Elimination - 'A' is **row equivalent** to \mathbb{I}
- $\det(A) \neq 0$

Solution methods

- Gaussian Elimination
- Matrix - vector / inverse method.

Determinant

- Used to determine if a matrix has an inverse
- Alternatively, if a system has a solution.

Computing the Determinant

- For a 2×2 or 3×3 , use method of diagonals.
- For an $n \times n$, use expansion by minors on a row.
- Use expansion by minors on a column.
- Use row reduction to simplify first!
 - Can be used to get a row or column of mostly zeros!

Determinant and System Solutions

- Not only can the determinant be used to see if a system has a solution.
- It can be directly used to compute the solution.
- **Cramer's Rule**

Methods of Solving a Linear System

- Gaussian Elimination
 - Best if you need to solve a system only once.
- Matrix - vector method.
 - Best if you need to solve a system many times.
- Cramer's Rule
 - Best if you need only one component of a solution, say x_5 .